(12) PATENT APPLICATION PUBLICATION

(19) INDIA

(22) Date of filing of Application :12/11/2022

(21) Application No.202211064849 A

(43) Publication Date: 02/12/2022

(54) Title of the invention: AUTOMATIC MESH WIRE MANUFACTURING DEVICE

:A61B0017120000, H01R0043033000,

A61B0034000000, A44C0027000000,

B21F0027120000

:NA

: NA

:NA

:NA

(71) Name of Applicant:

1) Jaipur National University

Address of Applicant :Jaipur-Agra Bypass, Near New RTO office, Jagatpura, Jaipur- 302017, Rajasthan, India. Jaipur -------

Name of Applicant: NA Address of Applicant: NA (72)Name of Inventor:

1)Rahul Agarwal

Address of Applicant :School of Engineering & Technology, Jaipur National University, Jaipur-Agra Bypass, Near New RTO office, Jagatpura, Jaipur- 302017, Rajasthan, India. Jaipur -------

2) Rahul Saxena

Address of Applicant: School of Engineering & Technology, Jaipur National University, Jaipur-Agra Bypass, Near New RTO office, Jagatpura, Jaipur- 302017, Rajasthan, India. Jaipur -------

3)Vikas Bansal

Address of Applicant: School of Engineering & Technology, Jaipur National University, Jaipur-Agra Bypass, Near New RTO office, Jagatpura, Jaipur- 302017, Rajasthan, India. Jaipur ------

4)Puneet Kalia

Address of Applicant :School of Engineering & Technology, Jaipur National University, Jaipur-Agra Bypass, Near New RTO office, Jagatpura, Jaipur- 302017, Rajasthan, India. Jaipur ------

(57) Abstract:

(51) International

(86) International

Filing Date (87) International

Filing Date (62) Divisional to

Application Number

Filing Date

(61) Patent of Addition:NA

to Application Number :NA

Application No

Publication No

classification

An automatic mesh wire manufacturing device comprises of a platform 1 arranged with an inverted U-shaped frame 2 for placing a motorized roller 3 that is wrapped with a metal wire to wrap/unwrap the wire, a touch enabled screen 4 to provide input commands relating the length and number of turns of a mesh wire, detachable telescopically operated rods 5 to position an elongated member 6, a telescopically operated gripper 7 to wrap a free-end of the wire on the member 6, a motorized slider 8 to translate the roller 3, a robotic arm 9 to position the cutter 10 and cut the wire, an electromagnet to detach the rod 5 from the member 6, a mechanical arm 11 to wrap the wire at a second end of the member 6 and an ultrasonic sensor to detect the length of the wire.

No. of Pages: 16 No. of Claims: 5

Jahur National University